

# Optimal Combinations of Realised Volatility Estimators

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- The development of new estimators of asset price variability has been a very active area of research in the past decade
  - See Andersen, *et al.* (2006) or Barndorff-Nielsen and Shephard (2007) for recent reviews of the literature on realised volatility estimators.
- Issues considered by papers in this area:
  - Accuracy of estimators based on higher frequency data
  - Efficiency
  - Robustness to microstructure effects
  - Ability to distinguish the continuous and the 'jump' components of variation
  - Estimation of covariances and correlations

## Partial list of papers in this area

- French, *et al.* (1987)
- Zhou (1996)
- Andersen and Bollerslev (1998)
- Andersen, Bollerslev, Diebold and Labys (2001, 2003)
- Barndorff-Nielsen and Shephard (2004, 2004, 2006)
- Aït-Sahalia, Mykland and Zhang (2005), ZMA (2005)
- Hansen and Lunde (2006)
- Christensen and Podolskij (2007), Martens and van Dijk (2007)
- Bandi and Russell (2006, 2008)
- Christensen, Oomen and Podolskij (2008)
- Barndorff-Nielsen, Hansen, Lunde and Shephard (2009)

*amongst many others*

# This paper's main question

★ *Do combinations of RV estimators offer gains in accuracy relative to individual estimators?*

- This question is motivated by the success of combinations in forecasting applications, see Bates and Granger (1969), Stock and Watson (2004), and Timmermann (2006) for example.
- Why do combination forecasts work well? From Timmermann (2006):
  - ① Combine information from each individual forecast: *directly applies to volatility estimation*
  - ② Average across differences in impact of structural breaks: *directly applies to volatility estimation*
  - ③ Less sensitive to model mis-specification: *applies to volatility estimation in terms of assumptions used to obtain specific estimators*

# Contribution of this paper

- 1 We propose methods for constructing theoretically optimal combinations of RV estimators, in terms of average accuracy.
  - This problem is non-standard, as the target variable (the quadratic variation of the process) is unobservable
  - Uses an extension of the data-based ranking method in Patton (2008), which avoids the need to make strong assumptions about the underlying price process.
- 2 We apply these methods to a collection of 32 different realised measures, across 8 distinct classes of estimators, using data on IBM from 1996-2008.
  - We use the step-wise testing method of Romano and Wolf (2005) and the MCS of Hansen, Lunde and Nason (2005) to identify best individual estimators, and to compare them with combination estimators.
  - We compare these estimators both in terms of in-sample accuracy, and in an out-of-sample forecasting experiment.

# Notation

|                              |   |
|------------------------------|---|
| $\theta_t$                   | the $\mathcal{F}_t$ -meas. latent target variable, eg: $QV_t$ or $IV_t$       |
| $X_{it}, i = 1, 2, \dots, n$ | the $\tilde{\mathcal{F}}_t$ -meas. realised volatility estimators             |
| $m$                          | the number of intra-daily observations  |
| $T$                          | the number of daily observations  |
| $L(\theta, X)$               | the pseudo-distance measure   |
| $\tilde{\theta}_t$           | a $\tilde{\mathcal{F}}_t$ -meas., noisy, but unbiased estimator of $\theta_t$ |
| $Y_t$                        | the proxy or instrument for $\theta_t$  |

# The pseudo-distance measure

- We measure accuracy using the average distance between the estimator and the quantity of interest:

$$\begin{array}{ll} \text{Infeasible} & E [L (\theta_t, X_{it})] \begin{array}{l} \geq \\ \leq \end{array} E [L (\theta_t, X_{jt})] \\ \text{Feasible} & E [L (Y_t, X_{it})] \begin{array}{l} \geq \\ \leq \end{array} E [L (Y_t, X_{jt})] \end{array}$$

where  $Y_t$  is the proxy for  $\theta_t$ .

- General results are given for the class of pseudo-distance measures proposed in Patton (2006). Empirical results use MSE or QLIKE:

$$\begin{array}{ll} \text{MSE} & L (\theta, X) = (\theta - X)^2 \\ \text{QLIKE} & L (\theta, X) = \frac{\theta}{X} - \log \frac{\theta}{X} - 1 \end{array}$$

# Combinations of RV estimators

- Let  $\mathbf{X}_t = [X_{1t}, \dots, X_{nt}]'$  be the vector of all  $n$  individual RV estimators, and consider a parametric combination of these:

$$X_t^{combo} = g(\mathbf{X}_t; \mathbf{w})$$

$$\text{eg 1 } g(\mathbf{X}_t; \mathbf{w}) = w_0 + \sum_{i=1}^n w_i X_{it}$$

$$\text{eg 2 } g(\mathbf{X}_t; \mathbf{w}) = w_0 \times \prod_{i=1}^n X_{it}^{w_i}$$

- Optimal* combinations:

$$\mathbf{w}^* \equiv \arg \min_{\mathbf{w} \in \mathcal{W}} E[L(\theta_t, g(\mathbf{X}_t; \mathbf{w}))]$$

$$\tilde{\mathbf{w}}^* \equiv \arg \min_{\mathbf{w} \in \mathcal{W}} E[L(Y_t, g(\mathbf{X}_t; \mathbf{w}))]$$

$$\hat{\mathbf{w}}_T^* \equiv \arg \min_{\mathbf{w} \in \mathcal{W}} \frac{1}{T} \sum_{t=1}^T L(Y_t, g(\mathbf{X}_t; \mathbf{w}))$$



# Assumptions for the main theoretical result

- In addition to standard regularity conditions, we require:

**Assumption P1:**  $E[\tilde{\theta}_t | \theta_t, \mathcal{F}_{t-1}] = \theta_t$ , where  $\mathcal{F}_{t-1}$  is info set generated by complete path of log-price process.

**Assumption P2:**  $Y_t = \sum_{j=1}^J \lambda_j \tilde{\theta}_{t+j}$ , for  $1 \leq J < \infty$ ,  $\lambda_j \geq 0 \forall j$ , and  $\sum_{j=1}^J \lambda_j = 1$ .

**Assumption T1:**  $\theta_t = \theta_{t-1} + \eta_t$ , where  $E[\eta_t | \mathcal{F}_{t-1}] = 0$

- The first assumption is reasonable, if we believe squared daily returns to be noisy but unbiased estimators of QV
  - In presence of jumps some care is required to find a proxy for IV.
- The third assumption is stronger. Critical for the result is that  $\theta_t$  is persistent. This can be captured either through a RW approximation (as above) or an AR approximation.

# Optimal combinations of RV estimators

**Proposition:** Under assumptions P1, P2, T1 and regularity conditions, and if  $L$  is a member of the class of distance measures in Patton (2006), then  $\tilde{\mathbf{w}}^* = \mathbf{w}^*$  and:

$$\hat{V}_T^{-1/2} \sqrt{T} (\hat{\mathbf{w}}_T^* - \mathbf{w}^*) \xrightarrow{D} N(0, I), \text{ as } T \rightarrow \infty$$

- Thus we can estimate the optimal combination parameter and overcome the fact that the target variable is latent.

# Application to estimating IBM price variability

- We apply this method to estimating the variability of open-to-close returns on IBM, over Jan 1996 to July 2008, 3168 trading days.
- We consider a total of 32 individual RV estimators from 8 distinct classes of estimators
  - For each estimator we follow the implementation of the authors of the original paper as closely as possible (and in most cases exactly)
- We compare these individual estimators with 3 simple combination estimators (arithmetic mean, median, and geometric mean)
- We compare accuracy both using the previous method for estimating (in-sample) accuracy, and using an out-of-sample forecasting experiment

# Description of the estimators I

- 1 **Realised variance:**  $RV_t^{(m)} = \sum_{j=1}^m r_{t,j}^2$ 
  - Sampling frequency: 1sec, 5sec, 1min, 5min, 1hr and 1day
  - Sampling method: calendar time and tick time (Hansen and Lunde 2006, Oomen 2006)
  - Bandi and Russell's (2006, 2008) MSE-optimal frequency (in calendar time), with and without their bias correction
- 2 **First-order autocorrelation adjusted RV**, as in French, *et al.* (1987), Zhou (1996), Hansen and Lunde (2006), Bandi and Russell (2008)
  - Estimated on 1min and 5min returns, in calendar time.
- 3 **Two-scale RV** of Zhang, *et al.* (2006) and **Multi-scale RV** of Zhang (2006)
  - 1tick and 1min tick-time frequencies

# Description of the estimators II

- 4 **Realised kernels** of Barndorff-Nielsen, *et al.* (2008), using their optimal bandwidth for each kernel
  - Kernels: Bartlett, Cubic, modified Tukey-Hanning<sub>2</sub>, non-flat-top Parzen
  - 1tick and 1min tick-time sampling
- 5 **Realised range**-based RV of Christensen and Podolskij (2007) and Martens and van Dijk (2007)
  - Using 5min blocks, and 1min prices within each block, similar to Christensen and Podolskij.
- 6 **Bi-power variation** of Barndorff-Nielsen and Shephard (2006).
  - 1min and 5min sampling, in calendar time
- 7 **Quantile-based realised variance** of Christensen, *et al.* (2008)
  - Using quantiles of 0.85, 0.90, and 0.96. Number of sub-intervals=1.
  - Prices sampled every 1min in tick time
- 8 **MinRV** and **MedRV** of Andersen, *et al.* (2008):
  - Using 1min tick time sampling

## Summary statistics on a sub-set of the estimators

|                          | Mean  | Standard<br>Deviation | Skewness | Kurtosis | Minimum |
|--------------------------|-------|-----------------------|----------|----------|---------|
| $RV^{1 \text{ sec}}$     | 3.158 | 3.005                 | 2.940    | 22.270   | 0.168   |
| $RV^{1 \text{ min}}$     | 2.438 | 2.387                 | 3.647    | 34.193   | 0.116   |
| $RV^{1 \text{ day}}$     | 2.403 | 6.228                 | 10.638   | 193.816  | 0.000   |
| $RV^{AC1,1 \text{ min}}$ | 2.440 | 2.392                 | 3.592    | 32.743   | 0.117   |
| $TSRV^{tick}$            | 2.177 | 2.202                 | 3.994    | 39.384   | 0.081   |
| $MSRV^{tick}$            | 2.181 | 2.287                 | 5.572    | 85.553   | 0.081   |
| $RK^{TH2}$               | 2.381 | 2.784                 | 7.761    | 158.827  | 0.109   |
| RRV                      | 2.310 | 2.537                 | 4.647    | 52.061   | 0.123   |
| $BPV^{1 \text{ min}}$    | 2.105 | 2.075                 | 2.632    | 12.867   | 0.077   |
| QRV                      | 2.441 | 2.273                 | 2.430    | 11.563   | 0.104   |
| MedRV                    | 2.260 | 2.157                 | 2.600    | 13.216   | 0.109   |

# Correlation between a sub-set of the estimators

|                       | $RV^{1\text{ sec}}$ | $RV^{5\text{ min}}$ | $RV^{1\text{ day}}$ | $RV^{AC1\text{ min}}$ | $RK^{TH2,1\text{ min}}$ | QRV   |
|-----------------------|---------------------|---------------------|---------------------|-----------------------|-------------------------|-------|
| $RV^{1\text{ sec}}$   | 1                   | 0.855               | 0.431               | 0.939                 | 0.839                   | 0.906 |
| $RV^{1\text{ min}}$   | 0.938               | 0.948               | 0.517               | 0.997                 | 0.939                   | 0.956 |
| $RV^{1\text{ day}}$   | 0.431               | 0.570               | 1                   | 0.514                 | 0.593                   | 0.483 |
| $RV^{AC1\text{ min}}$ | 0.939               | 0.947               | 0.514               | 1                     | 0.939                   | 0.955 |
| $TSRV^{tick}$         | 0.913               | 0.938               | 0.507               | 0.983                 | 0.931                   | 0.935 |
| $MSRV^{tick}$         | 0.904               | 0.952               | 0.519               | 0.980                 | 0.945                   | 0.913 |
| $RK^{TH2}$            | 0.874               | 0.975               | 0.550               | 0.967                 | 0.974                   | 0.885 |
| RRV                   | 0.902               | 0.984               | 0.550               | 0.982                 | 0.974                   | 0.933 |
| $BPV^{1\text{ min}}$  | 0.912               | 0.878               | 0.478               | 0.960                 | 0.871                   | 0.974 |
| QRV                   | 0.906               | 0.872               | 0.483               | 0.955                 | 0.867                   | 1     |
| MedRV                 | 0.919               | 0.882               | 0.487               | 0.961                 | 0.874                   | 0.980 |

# In-sample performance of the estimators

The data-based ranking method of Patton (2008) requires some choices:

- 1 We use a one-period lead of  $RV^{5 \text{ min}}$  as our instrument for the latent quadratic variation
  - Using a lower frequency (eg  $RV^{1 \text{ day}}$ ) reduces the power of tests
  - Using a higher frequency risks violating the unbiasedness assumption
- 2 We will present results using QLIKE; results using MSE are in a web appendix.
  - Results are broadly similar, though power is lower using MSE than using QLIKE
- 3 We use the RW approximation rather than an AR approximation to the dynamics in QV
  - This was found to be satisfactory in Patton (2008) on the same data
  - AR approximation leads to similar results, though with less precision



# In-sample performance of a sub-set of the estimators

|                        | Avg $\Delta$ QLIKE | Rank |       |       | In MCS? |      |
|------------------------|--------------------|------|-------|-------|---------|------|
|                        | Full               | Full | 96-99 | 00-03 | 04-08   | Full |
| $RV^{1\text{sec}}$     | -0.013             | 14   | 6     | 28    | 21      | —    |
| $RV^{1\text{min}}$     | -0.040             | 2    | 3     | 3     | 1       | ✓    |
| $RV^{1\text{day}}$     | 29.191             | 35   | 35    | 35    | 35      | —    |
| $RV^{AC1,1\text{min}}$ | -0.040             | 1    | 2     | 2     | 2       | ✓    |
| $TSRV^{tick}$          | -0.001             | 22   | 27    | 15    | 20      | —    |
| $MSRV^{tick}$          | -0.003             | 21   | 26    | 17    | 19      | —    |
| $RK^{TH2}$             | -0.014             | 12   | 16    | 11    | 9       | —    |
| $RRV$                  | -0.016             | 9    | 15    | 8     | 16      | —    |
| $BPV^{1\text{min}}$    | 0.029              | 28   | 31    | 12    | 8       | —    |
| $QRV$                  | -0.035             | 4    | 4     | 5     | 4       | —    |
| $MedRV$                | -0.024             | 6    | 9     | 6     | 10      | —    |
| $RV^{Mean}$            | -0.030             | 5    | 8     | 4     | 3       | —    |
| $RV^{Geo-mean}$        | -0.015             | 10   | 12    | 13    | 18      | —    |
| $RV^{Median}$          | -0.020             | 8    | 11    | 7     | 6       | —    |

# In-sample Romano-Wolf tests

| Benchmark:             | $RV^{1\text{day}}$ | $RV^{5\text{min}}$ | $RV^{Mean}$ |
|------------------------|--------------------|--------------------|-------------|
| Sample period          | Full               | Full               | Full        |
| $RV^{1\text{sec}}$     | ✓                  | –                  | ×           |
| $RV^{1\text{min}}$     | ✓                  | ✓                  | ✓           |
| $RV^{1\text{day}}$     | ★                  | ×                  | ×           |
| $RV^{AC1,1\text{min}}$ | ✓                  | ✓                  | ✓           |
| $TSRV^{tick}$          | ✓                  | –                  | ×           |
| $MSRV^{tick}$          | ✓                  | –                  | ×           |
| $RK^{TH2}$             | ✓                  | ✓                  | ×           |
| RRV                    | ✓                  | ✓                  | ×           |
| $BPV^{1\text{min}}$    | ✓                  | ×                  | ×           |
| QRV                    | ✓                  | ✓                  | –           |
| MedRV                  | ✓                  | ✓                  | ×           |
| $RV^{Mean}$            | ✓                  | ✓                  | ★           |
| $RV^{Geo-mean}$        | ✓                  | ✓                  | ×           |
| $RV^{Median}$          | ✓                  | ✓                  | ×           |

# Optimal combinations of RV estimators

- In the paper we present estimated optimal linear combination weights across the 32 individual estimators, but no clear patterns emerge (unsurprising given multicollinearity)
- The estimated optimal combinations can also be used to test the optimality of the equally-weighted average:

$$H_0 : w_0^* = 0 \cap w_1^* = \dots = w_n^* = 1/n$$

vs.  $H_a : w_0^* \neq 0 \cup w_i^* \neq 1/n \text{ for some } i = 1, 2, \dots, n$

⇒ This null is rejected with a  $p$ -value of less than 0.001

- Thus while a simple mean does well, it is possible to construct more accurate combination estimators.

# Encompassing of RV estimators

- We can also test whether a single estimator “encompasses” all others, in the same spirit as Chong and Hendry (1986) and Fair and Shiller (1990):

$$H_0^i : w_i^* = 1 \cap w_j^* = 0 \quad \forall j \neq i$$

vs.  $H_a^i : w_i^* \neq 1 \cup w_j^* \neq 0$  for some  $j \neq i$

⇒ This null is rejected *for every single estimator*, with  $p$ -values all less than 0.001.

- This is very strong evidence for considering combination RV estimators: no single estimator dominates all others.

# Out-of-sample comparisons of RV estimators

- We next consider comparing each of these estimators via a standard forecast experiment.
- We use the HAR model of Corsi (2004):

$$\tilde{\theta}_t = \beta_{0i} + \beta_{Di} X_{it-1} + \beta_{Wi} \frac{1}{5} \sum_{j=1}^5 X_{i,t-j} + \beta_{Mi} \frac{1}{22} \sum_{j=1}^{22} X_{i,t-j} + \varepsilon_{it}$$

- We use Jan 1996 - Dec 1999 as the initial estimation period, and then re-estimate each day using a rolling window of 1011 days.
  - We again use  $RV^{5\min}$  as the volatility proxy
- This is then a standard volatility forecasting problem, and we can compare the forecasts using existing methods.

# Out-of-sample performance of a sub-set of the estimators

|                          | Avg. $\Delta$ QLIKE | Rank |       |       | In MCS? |
|--------------------------|---------------------|------|-------|-------|---------|
|                          |                     | Full | 00-03 | 04-08 | Full    |
| $RV^{1 \text{ sec}}$     | 0.006               | 33   | 29    | 33    | –       |
| $RV^{1 \text{ min}}$     | -0.012              | 3    | 5     | 6     | ✓       |
| $RV^{AC1,1 \text{ min}}$ | -0.013              | 1    | 3     | 9     | ✓       |
| $TSRV^{tick}$            | -0.002              | 17   | 19    | 13    | –       |
| $MSRV^{tick}$            | 0.001               | 23   | 31    | 14    | –       |
| $RK^{TH2}$               | 0.003               | 30   | 33    | 25    | –       |
| RRV                      | -0.011              | 7    | 9     | 7     | ✓       |
| $BPV^{1 \text{ min}}$    | -0.007              | 10   | 6     | 15    | –       |
| QRV                      | -0.007              | 13   | 1     | 31    | –       |
| MedRV                    | -0.007              | 12   | 2     | 28    | –       |
| $RV^{Mean}$              | -0.012              | 4    | 10    | 2     | ✓       |
| $RV^{Geo-mean}$          | -0.013              | 2    | 11    | 1     | ✓       |
| $RV^{Median}$            | -0.011              | 6    | 12    | 4     | –       |
| $FCAST^{Mean}$           | -0.006              | 15   | 15    | 10    | –       |
| $FCAST^{Geo-mean}$       | -0.007              | 14   | 14    | 8     | –       |
| $FCAST^{Median}$         | -0.005              | 16   | 16    | 11    | –       |

# Out-of-sample Romano-Wolf tests

| Benchmark:             | $RV^{1\text{day}}$ | $RV^{5\text{min}}$ | $RV^{Mean}$ | $FCAST^{Mean}$ |
|------------------------|--------------------|--------------------|-------------|----------------|
| Sample:                | Full               | Full               | Full        | Full           |
| $RV^{1\text{sec}}$     | ✓                  | –                  | ×           | ×              |
| $RV^{1\text{min}}$     | ✓                  | ✓                  | –           | ✓              |
| $RV^{AC1,1\text{min}}$ | ✓                  | ✓                  | –           | ✓              |
| $TSRV^{tick}$          | ✓                  | –                  | ×           | –              |
| $MSRV^{tick}$          | ✓                  | –                  | ×           | ×              |
| $RK^{TH2}$             | ✓                  | –                  | ×           | ×              |
| RRV                    | ✓                  | ✓                  | –           | ✓              |
| $BPV^{1\text{min}}$    | ✓                  | –                  | –           | –              |
| QRV                    | ✓                  | –                  | –           | –              |
| MedRV                  | ✓                  | –                  | –           | –              |
| $RV^{Mean}$            | ✓                  | ✓                  | ★           | ✓              |
| $RV^{Geo-mean}$        | ✓                  | ✓                  | –           | ✓              |
| $RV^{Median}$          | ✓                  | ✓                  | –           | ✓              |
| $FCAST^{Mean}$         | ✓                  | ✓                  | ×           | ★              |
| $FCAST^{Geo-mean}$     | ✓                  | ✓                  | ×           | ✓              |
| $FCAST^{Median}$       | ✓                  | ✓                  | ×           | –              |

## Combine estimators or combine forecasts?

- An interesting question arises on whether it is better to use a combination RV estimator in the HAR model and then forecast, or to estimate HAR models on individual RV estimators and then combine the forecasts.
- We compare HAR forecasts using  $RV^{Mean}$ ,  $RV^{Geo-mean}$  and  $RV^{Median}$  with combination forecasts  $FCAST^{Mean}$ ,  $FCAST^{Geo-mean}$ , and  $FCAST^{Median}$  using a simple Diebold-Mariano (1995) test

Mean  $DM\ t\text{-stat} = 7.66$

Geo-mean  $DM\ t\text{-stat} = 7.10$

Median  $DM\ t\text{-stat} = 6.49$

- Thus we find strong evidence that estimating a single HAR model on a combination RV estimator dominates using a forecast combination based on many individual forecasts.



## Conclusion and summary of results

- This paper's main question: *Do combinations of RV estimators offer gains in accuracy relative to individual estimators?* → **Yes!**
- Using a new method for comparing RV estimator accuracy and a standard out-of-sample forecast experiment, we find that combination RV estimators significantly outperform individual estimators.
  - In-sample, only two estimators ( $RV^{1\min}$  and  $RV^{AC1\min}$ ) significantly out-perform a simple equally-weighted average RV estimator.
  - Out-of-sample, no estimator significantly out-performs a simple equally-weighted average RV estimator.
- Further, no single RV estimator encompassed the information available in all other estimators, providing additional support for combination realised measures.